Hits   Search Text   DB	6
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT   Secondary	6
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT   Secondary	6 6
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWENT US-PGPUB I6:10  113 (382/153).CCLS.) and (inspect\$3 or USPAT; measur\$3 or measurement) US-PGPUB USPAT; US-PGPUB 16:20 USPAT; US-PGPUB 16:20 USPAT; US-PGPUB 16:20 USPAT; US-PGPUB 16:26 USPAT; US-PGPUB 16:26	6 6
TBM_TDB	6 6
- 1 JP-04075887-\$.did. USPĀT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPĀT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPĀT; US-PGPUB; EPO; JPO; DERWENT - 89 ((382/153).CCLS.) and (inspect\$3 or measur\$3 or measurement) USPĀT; 2004/04/2 US-PGPUB 16:16 - 113 (382/153).CCLS.) and (learn\$3 or teach\$3 or USPĀT; 2004/04/2 US-PGPUB 16:20 - 51 ((382/153).CCLS.) and (learn\$3 or teach\$3 or registered or registering or registering or registration) USPĀT; 2004/04/2 US-PGPUB 16:26	6 6
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; 2004/04/2 US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; 2004/04/2 US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWENT US-PGPUB 16:16 USPAT; 2004/04/2 US-PGPUB 16:16 USPAT; 2004/04/2 US-PGPUB 16:20 USPAT; 2004/04/2 US-PGPUB 16:20 USPAT; 2004/04/2 US-PGPUB 16:20 USPAT; 2004/04/2 US-PGPUB 16:26 USPAT; 2004/04/2 US-PGPUB 16:26 USPAT; 2004/04/2 US-PGPUB 16:26	6 6
EPO; JPO; DERWENT; IBM_TDB USPAT; 2004/04/2 US-PGPUB; EPO; JPO; DERWENT  - 89 ((382/153).CCLS.) and (inspect\$3 or measur\$3 or measurement) USPAT; 2004/04/2 US-PGPUB 16:16  - 113 (382/153).CCLS. USPAT; 2004/04/2 US-PGPUB 16:20  - 51 ((382/153).CCLS.) and (learn\$3 or teach\$3 or USPAT; 2004/04/2 US-PGPUB 16:20  - 51 ((382/153).CCLS.) and (learn\$3 or teach\$3 or teach\$3 or registered or registering or registration)  - 7 arimatsu-taro.in. USPAT; 2004/04/2	6
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB 16:16 USPAT; US-PGPUB 16:20 US-PGPUB 16:26	6
TDB	6
- 2 WO-9942257-\$.did. USPĀT; 2004/04/2 US-PGPUB; 15:03  - 89 ((382/153).CCLS.) and (inspect\$3 or USPAT; 2004/04/2 US-PGPUB 16:16 - 113 (382/153).CCLS. USPAT; 2004/04/2 US-PGPUB 16:20 - 51 ((382/153).CCLS.) and (learn\$3 or teach\$3 or teach\$3 or registered or registering or registration) - 7 arimatsu-taro.in. USPAT; 2004/04/2	6
US-PGPUB; 15:03  US-PGPUB; EPO; JPO; DERWENT  US-PGPUB 16:16  US-PGPUB 16:16  US-PGPUB 16:16  US-PGPUB 16:20  US-PGPUB 16:26  US-PGPUB 16:26  US-PGPUB 16:26	6
- 89 ((382/153).CCLS.) and (inspect\$3 or measur\$3 or measurement)	6
- 89 ((382/153).CCLS.) and (inspect\$3 or measur\$3 or measurement)	6
measur\$3 or measurement)	6
- 113 (382/153).CCLS. USPAT; 2004/04/2 US-PGPUB 16:20 - 51 ((382/153).CCLS.) and (learn\$3 or teach\$3 USPAT; 2004/04/2 Or registered or registering or registration) - 7 arimatsu-taro.in. USPAT; 2004/04/2	
US-PGPUB   16:20	
- 51 ((382/153).CCLS.) and (learn\$3 or teach\$3 USPAT; 2004/04/2 or registered or registering or registration) - 7 arimatsu-taro.in. USPAT; 2004/04/2	_
or registered or registering or US-PGPUB 16:26 registration) 7 arimatsu-taro.in. USPAT; 2004/04/2	<b>h</b> 1
registration) 7 arimatsu-taro.in. USPAT; 2004/04/2	,
- 7 arimatsu-taro.in. USPAT; 2004/04/2	
IIG_DCDITD 16.40	6
- 2 JP-2000288968-\$.did. USPAT; 2004/04/2	6
US-PGPUB; 16:39	
EPO; JPO;	
DERWENT;   IBM TDB	
- 2 EP-1043126-\$.did. USPAT; 2004/04/2	7
US-PGPUB; 09:38	•
EPO; JPO;	
DERWENT	
- 17 (382/\$.ccls. 901/\$.ccls.) and USPAT; 2004/04/2	6
watanabe-atsushi.in. US-PGPUB 16:41	_
- 54 watanabe-atsushi.in. and fanuc\$.as. USPAT; 2004/04/2	ь
US-PGPUB 16:43 - 197 (382/152).CCLS. USPAT; 2004/04/2	6
US-PGPUB 16:48	-
- 39 ((382/152).CCLS.) and robot\$3 USPAT; 2004/04/2	6
US-PGPUB 16:55	
- 67 ((382/151).CCLS.) and robot\$3 USPAT; 2004/04/2	6
US-PGPUB 17:04	_
- 18 ((plural\$3 or multiple or dual or two or USPAT; 2004/04/2	ь
several or many) adj robot\$3) same (video US-PGPUB; 17:07	
or camera or CCD or image or visual) same EPO; JPO; (workpiece or work-piece or (work adj DERWENT;	
part or piece) or model) IBM TDB	
- 138 ((382/151-154).CCLS.) and (recogni\$6 or USPAT; 2004/04/2	6
identif\$3 or identification) same robot\$3 US-PGPUB 17:08	
- 135 ((plural\$3 or multiple or dual or two or USPAT; 2004/04/2	6
several or many) adj robot\$3) and (video US-PGPUB; 17:24	
or camera or CCD or image or visual) same EPO; JPO;	
(workpiece or work-piece or (work adj DERWENT;	
part or piece) or model1\$3)   IBM_TDB   - 25   robot\$3 same (camera or visual or CCD or USPAT;   2004/04/2	6
optical) same (ax\$s with rotat\$3 with US-PGPUB; 17:37	5
(perpendicular or orthogonal)) EPO; JPO;	
DERWENT;	
IBM_TDB	
- 17 ((382/154).CCLS.) and (reference or USPAT; 2004/04/2	6
register\$3 or registration or teach\$3 or US-PGPUB 17:38	
train\$3 or learn\$3) with (object or model	
or part or workpiece or work-piece or	
work adj piece) same robot\$3  - 60 901/47.ccls. and (workpiece or (work adj USPAT; 2004/04/2	6
piece) or model or part) with (position US-PGPUB 17:38	~
or location) with (posture or orientation	
or arrangement)	

			_	
_	25	901/47.ccls. and (plural\$3 or multiple or several or many) with (video or camera or CCD or image or visual) same (workpiece	USPAT; US-PGPUB	2004/04/26 17:38
		or work-piece or (work adj part or piece) or model)		
-	1	("5446835").PN.	USPAT; US-PGPUB	2004/04/26 17:39
_	275	<pre>(robot with (camera or CCD or image or visual)) same (robot with (workpiece or work-piece or (work adj part or piece) or model))</pre>	USPAT; US-PGPUB	2004/04/27
_	2	WO-9201539-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/04/27 09:38
-	17	("3576997"   "4459526"   "4707647"   "4725965"   "4731860"   "4831549"   "4843561"   "4985846"   "5083073"   "5297238"   "5446835"   "5467517"   "5523663"   "5552575"   "5680694"   "5903663"   "5968297").PN.	USPAT	2004/04/27
	172	(382/\$.ccls. 348/\$.ccls. 356/\$.ccls. 700/\$.ccls. 901/\$.ccls.) and robot\$3 same (camera or CCD or imag\$3 or video) same (position\$3 or locat\$4 or (three or "3") adj dimension\$4 or 3D or 3-D or coordinate) with (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body)	USPAT; US-PGPUB	2004/04/28 10:53
-	1	("4305130").PN.	USPAT; US-PGPUB	2004/04/27 11:24
	162	(robot\$3 or effector or manipulator) same (camera or CCD or imag\$3 or video or visual) same (orientation or posture or attitude or pose or arrangement) same (compar\$5 or correlat\$4 or collat\$4 or match\$3 or correspond\$4) with (model or stor\$3 or taught or teaching or learn\$3 or reference or registered or registration or recogni\$6 or identif\$4 or template or target)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/28
_	2	EP-1043689-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/04/28 12:44
_	2	WO-9724206-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/04/28 16:04